Lung Nodule Classification Using Deep Features in CT Images

Devinder Kumar, Alexander Wong, and David A. Clausi





UNIVERSITY OF WATERLOO FACULTY OF ENGINEERING Department of Systems Design Engineering

June 5^{th} , 2015

Vision and Image Processing Research Group, UWaterloo

► < □ > < □ > < □</p>
CRV conference, 2015

Outline

- Why?
 - Motivation
- What?
 - Proposed Approach
- How?
 - Exp. Setup
- So, What?
 - Future Work

∃ → < ∃</p>

3

• Why?

- $\bullet\,$ Lung cancer results in 17% of total cancer related deaths.
- Early diagnosis required as it is harder to contain in later stages.
- Burden on doctors for early diagnosis.
- **Untapped data** is now available to build effective computer aided diagnosis (CAD) systems.
- Goal: second opinion!

Proposed Approach

• Build an effective CAD system to classify annotated nodules as malignant or benign using *deep* features extracted from autoencoder and binary decision tree as classifier.



Figure : Proposed system flow diagram

Vision and Image Processing Research Group, UWaterloo

CAD system Design : Dataset

- LIDC-IDRI dataset
 - Thoracic CT images of 1010 patients
 - Diagnostic data for 157 patients avialable (ground truth)
 - Ratings: 0-Unknown, 1-benign, 2-Primary malignant, 3-metastatic
 - Annotations provided!
 - Nodule size: 3 mm to 30 mm



(A) (C) (B) (D)
 Figure : Annotations provided by four different radiologists

Vision and Image Processing Research Group, UWaterloo

CAD system Design : Autoencoder

- Design:
 - Encoder
 - Decoder



Vision and Image Processing Research Group, UWaterloo

CRV conference, 2015

(*) *) *) *)

Let

- input be $f(x^i) \in [0,1]^d$
- latent space $y \in [0, 1]^d$
- ϕ be non linear function

$$y = \phi(Wf(x^i) + b) \tag{1}$$

Reconstruction:

$$f(x^{i})' = \phi(W'y + b')$$
⁽²⁾

• Error minimization:

$$\min_{W,b} \sum_{i=1}^{n} \| f(x^{i})' - f(x^{i}) \|^{2}$$
(3)

Vision and Image Processing Research Group, UWaterloo

CRV conference, 2015



Figure : Stacked autoencoder formation

Vision and Image Processing Research Group, UWaterloo

CRV conference, 2015

∃ >





Input Features II Output (Features I)

Figure : Stacked autoencoder formation

Vision and Image Processing Research Group, UWaterloo

CRV conference, 2015

→ 3 → < 3</p>





Input Features II Output (Features I)



(Features II) classifier

Figure : Stacked autoencoder formation





Input Features II Output (Features I)



Figure : Stacked autoencoder formation

- Our Design
 - 3 Hidden layers
 - layer size 200,100,200
 - Iteration set: 30
 - Batch size: 400
 - Feature extraction at 3rd hidden layer



Vision and Image Processing Research Group, UWaterloo

Experimental Setup

- Data: 4303 Instances (4323 nodules)
 - Obtained from diagnostic data
 - all provided annotation considered
 - Rating: 1: benign & 0,2,3: malignant
- Feature extraction: features are extracted from 4th layer (3rd hidden layer)
 - 200 dim. vector
- Training:
 - 90% of 4303 Instances
 - 10-fold cross validation

Results

• 10 fold cross validation avg. :

- Accuracy: 75.01
- Sensitivity: 83.35
- FP/patient: 0.39

	Deep Features	Belief Decision Trees ¹
Accuracy	75.01%	68.66%

¹D. Zinovev et al., Probabilistic lung nodule classification with belief decision trees in EMBC, 2011 Annual International Conference of the IEEE. IEEE, 2011, pp. 44934498

Vision and Image Processing Research Group, UWaterloo

Results:Dificult cases



Figure : significant visual similarities between the annotated nodules in (a,d), (b,e) and (c,f), making it very difficult to differentiate between such nodules during the classification process.

• So, What?

Vision and Image Processing Research Group, UWaterloo

CRV conference, 2015

→ 3 → 4 3

æ

- different deep architectures (e.g. CNN) & more hidden layers i.e. *very deep* networks (16-19 layers)
- combination of features
- STAPLE
- SPIE lung nodule classification challenge
- Automatic nodule detection

Thank you for listening!

Contact: Devinder Kumar Email: devinder.kumar@uwaterloo.ca

Vision and Image Processing Research Group, UWaterloo